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# Usage FlexPDE Package in the Courses of Mathematical Modeling and Mechanics

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## Well known Finite Element Packages



https://www.simuleon.com/simulia-abaqus/abaqus-explicit/ http://cae-expert.ru/product/ansys-cfx



# *<b>HABAQUS*

**Superior Finite Element Analysis Solutions** 

## MSC Nastran Structural & Multidiscipline FEA

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### **FlexPDE** Package



## Ansys | Abaqus | Nastran





## **Purposes and Possibilities**

#### The Course involves solving educational tasks using finite element packages

#### Using the finite element package FlexPDE allows to

- solve the problem described by differential equations in partial derivatives of the 1st and 2nd of orders
- determine the geometry and boundary conditions
- set accuracy of the solution
- set output method results



### **Necessary Educational Background**

- Differential equations
- Numerical methods
- Skills in Maple and MatLab packages
- Equations of mathematical physics
- Basics of theoretical mechanics
- Fundamentals of linear elasticity

- Stationary thermal conductivity
- Transient thermal conductivity
- Frequency analysis
- Determination of stress-strain state in the static problems of elasticity

## Areas of science where we can apply FlexPDE

- Physics
- Mechanics
- Chemistry
- Biology



Planetary motion Strain-Stress Solution Reaction-diffusion Microorganisms Colony Growth



#### The Problems described by the Poisson equation

- Thermal conductivity
- Hydraulics
- Electrostatics
- Physics

Poisson's equation

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = f(x, y)$$



## Main sections of FlexPDE script

TITLE COORDINATES VARIABLES DEFINITIONS **EQUATIONS** BOUNDARIES **MONITORS PLOTS END** 

- name of the task
- coordinate system
- variable of differential equations
- parameters of the problem
- differential equations
- boundaries and boundary conditions
- intermediate results
- final results
- end of program

## The example of FlexPDE script

```
TITLE 'Stationary Heat Conductivity'
COORDINATES
   cartesian3
SELECT
painted
VARIABLES u
DEFINITIONS
  K = 0.1
              { conductivity }
   R0 = 1
              { radius }
  H0 = 100 { total heat }
   heat =H0*exp(-x^2-y^2-z^2) { volume heat source }
EQUATIONS
   div(K^*grad(u)) + heat = 0
 extrusion
  surface z = -sqrt(R0^2 - (x^2+y^2)) \{ the bottom hemisphere \}
  surface z=0
  surface z = sqrt(R0^2 - (x^2 + y^2)) \{ the top hemisphere \}
BOUNDARIES
   surface 1 value(u) = 0
   surface 3 \text{ value}(u) = 0
   Region 1
    laver 1 K=0.1
    layer 2 K=0.5
    start (R0,0) arc(center=0,0) angle=360
PLOTS
   grid(x,y,z)
   contour(u) on x=0
END
```





#### Examples

- 1. Saint-Venant's principle
- 2. Typical tasks for students:
  - ✓ The Kirsch problem
  - ✓ Frequency analysis

## **Example 1. Saint-Venant's principle**



### Example 2. The Kirsch problem

#### **Tension of the Bar with a Hole**



## **Example 2. The Kirsch problem**

#### **Tension of the Bar with a Hole**



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## **Example 2. The Kirsch problem**

# **Individual tasks:** to analyze the dependence of stress-strain state from

- geometrical parameters
- physical parameters
- boundary conditions



#### La 1st octave. Frequency - 440 Hz





Tuning fork with resonator box

3D model of the fork

Equations of motion

Cauchy relations

$$\nabla \cdot \mathbf{\sigma} + \rho \mathbf{f} = \rho \frac{\partial^2 \mathbf{u}}{\partial t^2}$$
$$\varepsilon_{ij} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

Hooke's law

$$\sigma_{ij} = \lambda \theta + 2\mu \delta_{ij} \varepsilon_{ij}$$

#### **Boundary conditions**

- no forces on the side surface
- no motion at the sealing

Stationary problem

$$\mathbf{u}(x, y, z, t) = \mathbf{u}(x, y, z)\cos(\omega t)$$

 $\mathbf{n} \cdot \boldsymbol{\sigma} = 0$  $\mathbf{u} = 0$ 



#### COORDINATES

#### cartesian3 SELECT {numbers of frecuency} modes = 3 VARIABLES U1 U2 U3 { displacements } DEFINITIONS nu=0.3 E=200e9 lambda=E/(1+nu)/(1-2\*nu) mu=E/(2\*(1+nu))

```
{ Cauchy relation }
E11 = dx(U1)
E12 =(dy(U1) + dx(U2))/2
```

#### • • •

. . .

. . .

{ Hooke's law } S11=lambda\*((1-nu)\*E11+ nu\*E22) S12=mu\*E12

#### **EQUATIONS**

U1: dx(S11) + dy(S12) + dz(S31) + Omega\*rho\*U = 0U2: dx(S12) + dy(S22) + dz(S32) + Omega\*rho\*V = 0U3: dx(S13) + dy(S23) + dz(S33) + Omega\*rho\*W = 0

EXTRUSION z = 0, hBOUNDARIES region 1 start(0,0) { Boundary conditions } load(U1)=0 load(U2)=0 load(U3)=0 line to... PLOTS grid(x+U1, y+U2, z+U3) as "Shape"... summary report lambda END

#### **Possible complicating**



**Individual tasks:** to analyze the dependence of frequency from

- geometrical parameters
- physical parameters
- boundary conditions



Resonator

**3D** 

## **Additional tasks**

#### **Building of Geometry**



#### **Export and import of Data**

## **Additional tasks**

#### Influence of grid parameters on the accuracy of the solution



- ✓ CELL SIZE CONTROL
- ✓ MESH\_DENSITY
- ✓ MESH\_SPACING
- ✓ RESOLVE
- ✓ BDRY\_DENSITY
- ✓ ERRLIM

#### Analysis and further processing of the results

## **Additional tasks**

#### Influence of grid parameters on the accuracy of the solution

Status	
CPU time	0:08
Grid	1
Nodes	6243
Cells	4026
Unknowns	6243
Mem(K)	54349
RMS Error	1.228e-3
Max Error	4.647e-3
DONE	
_	
Status	
CPU time	2:05
Grid	8
Nodes	270194
Cells	188346
Unknowns	270194
Mem(K)	475046
Mem(K) RMS Error	475046 5.765e-5
Mem(K) RMS Error Max Error	475046 5.765e-5 4.154e-4



select
 { error limit }
 errlim=1e-2
 { mesh size }
 ngrid=2

select
{ error limit }
errlim=1e-4
{ mesh size }
ngrid=4

# Conclusion

#### So why we like FlexPDE package so much?

- Student version is free
- The transparency of BVP solving allows to
  - better absorb the course material
  - understand the essence of the problem
  - propose new ideas and methods of solution
  - attract additional math for solving complex problems

# THANK YOU!

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